Lesson Plan

| Name (| of the Institute: | C. V. Raman Polytechnic | |
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| Depart | ment: | Mechanical Engineering | |
| Semest | er/Division/Branch: | 1st & 2nd | |
| Subjec | t Name with code: | Engineering Mechanics | |
| Total N | No. of Class (Required): | 60 | |
| Faculty | y Name: | MS SUTAPA SARKAR | - |
| Class No. | Brief Description of the | · Topic/Chapter to be taught | Remarks |
| 1 | Definitions of Mechanics, Statics, | Dynamics, Rigid Bodies | |
| 2 | Basic concepts of Time, Space, Mass, Flexible body, rigid body, scalar quantity, vector quantity, Units of measurement (Fundamental units, Derived units, SI units) | | 1 st week |
| 3 | Force:- Introduction, units, chara | acteristics of force, effect of force. | |
| 4 | Force system & classification(col non-concurrent and non-parallel | linear, coplanar, parallel, concurrent, force system) | |
| 5 | Principles of Static force (Equi superposition of forces, principle | librium law of force, principle of e of transmissibility) | |
| 6 | Resolution of force (orthogonal components | components, non-orthogonal | |
| 7 | Composition of force (Resultant concurrent force system (a) Law triangle of force (c) Methods of | of parallelogram of force (b) law of | 2 nd Week |
| 8 | Composition of force (Resultant concurrent force system (a) Law triangle of force (c) Methods of | of parallelogram of force (b) law of | |
| 9 | | blems related to composition of forces. | 3 rd Week |

| | 11 | | |
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| | 10 | Solving various engineering problems related to composition of forces | |
| | 11 | Graphical Method. Introduction, Space diagram, Vector diagram, Polygon law of forces. | 3 rd Week |
| | 12 | Resultant of concurrent ,non-concurrent & parallel force system by Analytical & Graphical Method. | |
| | 13 | Moment of Force .Definition & its S.I units. Classification of moments according to direction of rotation, sign convention, Law of moments. | |
| 14 | | Varignon's Theorem, Couple–Definition, S.I. units ,measurement of couple, properties of couple. | 4 th week |
| | 15 | Equilibrium& Equilibrant, condition of equilibrium, freebody diagram. | |
| 4 | 16 | Lamia's theorm statement & prove. | |
| 2 | 17 | Lamia's theorem ,Application for solving various engineering problems. | |
| | 18 | Lamia's theorem ,Application for solving various engineering problems. | |
| | 19 | Types of supports, types of loading, Types of Beams | 5 th week |
| | 20 | Types of supports, types of loading, Types of Beams | |
| | 21 | Beam reactions (cantilever beam, simply supported, overhang beam) | |
| | 22 | Solving various engineering problems related to beam reactions. | |
| | 23 | Solving various engineering problems related to beam reactions. | 6 th week |
| | 24 | Friction and its types , Laws of friction, Advantages & Disadvantages of Friction. | |
| | 25 | Laws of friction, Advantages & Disadvantages of Friction. | |
| | 26 | Limiting friction, Normal reaction. | - 10 |
| がに | 27 | Co-efficient of friction, Angle of friction, Angle of repose. | 7 th week |
| 100 | Equilibrium of a bodies on level surface subjected to force parallel to plane. | | |
| | 29 | Equilibrium of a bodies on level surface subjected to force inclined to | |
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| (SALE) | nland the same of | |
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| | plane. | The second secon |
| 30 | Solving numericals. | 8 th week |
| 31 | Solving numericals. | |
| 32 | Revision. | |
| 33 | Center of gravity & Centroid (Definition & comparison), axes of reference. | |
| 34 | Centroid of standard shapes. | |
| 35 | Centroid of composite figures. | 9 th week |
| 36 | Centroid of geometrical figures such as squares, rectangles, triangles. | |
| 37 | Centroid of geometrical figures such as circles, semicircles & quarter circles. | |
| 38 | Center of gravity of simple solids (cylinder) | |
| 39 | Center of gravity of simple solids (cone) | 10 th week |
| 40 | Center of gravity of composite solids(sphere) | |
| 41 | Center of gravity of composite solids(hemisphere) | |
| 42 | Center of gravity of composite solids | |
| 43 | Center of gravity of composite solids | 11 th week |
| 44 | Revision. | |
| 45 | Definition of simple lifting machine, compound machine, load, effort . | |
| 46 | Define Mechanical advantages, Velocity ratio & Efficiency State the relation between them. | 12 th week |
| 47 | State Ideal machine, Friction in machine. | |
| 48 | State Maximum mechanical advantages and efficiency. | |
| 49 | Define Reversible machine & Non Reversible machine, conditions for reversibility | |
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| 50 | Define Reversible machine & Non Reversible machine, conditions for reversibility. | 13 th week |
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| 51 | Study of simple machines – Velocity ratio of simple axle & wheel & solving to numerical. | |
| 52 | Study of simple machines – Velocity ratio of Differential axle & wheel& solving numerical | |
| 53 | Study of simple machines – Velocity ratio of single purchase crab winch & solving numerical. | |
| 54 | Study of simple machines – Velocity ratio of Worm & Worm wheel & solving numerical. | 14 th week |
| 55 | Study of simple machines –Velocity ratio of Simple Screw Jack & solving numerical. | |
| 56 | Study of simple machines –Velocity ratio of Weston's differential pulley block | |
| 57 | Study of simple machines -Velocity ratio of Geared pulley block. | |
| 58 | Revision. | |
| 59 | Doubt clearing. | 15 th week |
| 60 | Doubt clearing. | |

Sulepa Sarua . Signature of the Faculty

Signature of the H.O.D

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